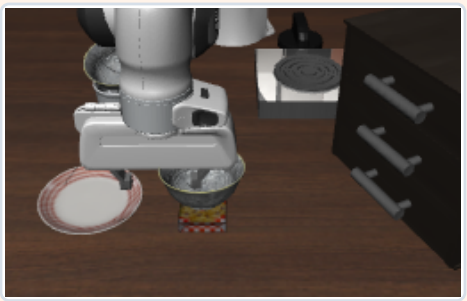
A successful discovery

Frozen $\pi_{0.5}$ · bowl → plate



(a) Wrong bowl

Close before correction

(b) Loop 1: expand

RGB-D + back-projection

Harness VLA → OpenVLA library

(c) Same sensors, policy, pairs

(d) Loop 2: compose

Grounded pick + recovery

(e) 400 fresh cases

263 → 275 / 400

12 wins · 0 losses

$p = 4.9 \times 10^{-4}$



DEV code + lessons → library